



Statistical Sciences
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Sensitivity Measures based on Scoring Functions

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joint work with

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Sensitivity Measures

- Probability space: $(\Omega, \mathfrak{F}, \mathbb{P})$
- Model: $Y = g(\mathbf{X})$
- $T: \mathcal{M}' \rightarrow A$ law-invariant functional of interest.
- \mathcal{M}' sets of probability measures on \mathbb{R}

Examples of T : Mean, mode, quantiles, Value-at-Risk, Expected Shortfall, law-invariant risk measures...

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Examples of T : Mean, mode, quantiles, Value-at-Risk, Expected Shortfall, law-invariant risk measures...

⇒ How to choose a sensitivity measure for T ?

Sensitivity Measures

- ◇ variance-based [Saltelli & Tarantola, 2002, Saltelli et al., 2008];
- ◇ moment-independent [Borgonovo, 2007];
- ◇ quantile-based sensitivities [Browne et al., 2017];
- ◇ based on divergence measures
[Gamboa et al., 2018, Pesenti et al., 2019, Fort et al., 2021]
- ◇ differential sensitivity measures [Tsanakas & Millossovich, 2016]
- ◇ Machine Learning & Interpretability
[Mase et al., 2021, Bénard et al., 2021]
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⇒ [Borgonovo et al., 2021] choice of a sensitivity measure should be tied to T via a **strictly consistent scoring functions** and thus reflect the **information value**.

A scoring function is a measurable map $S: A \times \mathbb{R} \rightarrow [0, \infty]$.

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For $T: \mathcal{M}' \rightarrow A$ and a sub-class $\mathcal{M} \subseteq \mathcal{M}'$, we say

(i) S is \mathcal{M} -consistent for T , if for all $F \in \mathcal{M}$ and for all $z \in A$

$$\int S(T(F), y) dF(y) \leq \int S(z, y) dF(y). \quad (1)$$

(ii) S is strictly \mathcal{M} -consistent for T , if it is \mathcal{M} -consistent for T and if (1) is strict for all $z \neq T(F)$.

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T is *elicitable* on \mathcal{M} , if there exists a strictly \mathcal{M} -consistent scoring function for T .

T	$S(z, y)$
mean	$(x - y)^2$
median	$ x - y $
VaR_α	$(\mathbb{1}_{\{y \leq z\}} - \alpha)(z - y)$
variance	NO
Expected Shortfall (ES)	NO
(mean, variance)	YES!
$(\text{VaR}_\alpha, \text{ES}_\alpha)$	YES!

Strictly consistent scoring functions respect increasing information sets:

If S is strictly consistent for T and $\mathfrak{A} \subseteq \mathfrak{F}$, then

$$\mathbb{E}[S(T(Y), Y)] - \mathbb{E}[S(T(Y|\mathfrak{A}), Y)] \geq 0.$$

- ◇ **resolution term** of the score decomposition [Pohle, 2020]
- ◇ **discrimination** [Gneiting & Resin, 2021]
- ◇ a special instance of a **score divergence** [Thorarinsdottir et al., 2013, Gneiting & Raftery, 2007]

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Sensitivity of Y to \mathfrak{A} based on S is given by¹

$$\xi_S(Y; \mathfrak{A}) = \frac{\mathbb{E}[S(T(Y), Y)] - \mathbb{E}[S(T(Y|\mathfrak{A}), Y)]}{\mathbb{E}[S(T(Y), Y)]} \in [0, 1].$$

E.g. $T() = \mathbb{E}[\cdot]$, $S(z, y) = (z - y)^2$, $\xi_S(Y; \mathfrak{A})$ are the Sobol indices.

¹technical assumptions on S

Zero information gain:

$T(Y|\mathfrak{A}) = T(Y)$ implies $\xi_S(Y; \mathfrak{A}) = 0$.

S is strictly consistent: $\xi_S(Y; \mathfrak{A}) = 0$ only if $T(Y|\mathfrak{A}) = T(Y)$.

◇ If Y and \mathfrak{A} are independent: $\xi_S(Y; \mathfrak{A}) = 0$

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- ◇ If Y and \mathfrak{A} are independent: $\xi_S(Y; \mathfrak{A}) = 0$
- ◇ $Y = X_1X_2 + X_3$; X_1, X_2, X_3 independent and $\mathbb{E}[X_2] = 0$.

Then,

$$T(Y|X_1) = \mathbb{E}[Y|X_1] = \mathbb{E}[X_3] = \mathbb{E}[Y] = T(Y)$$

and $\xi_S(Y; X_1) = 0$ for any consistent scoring function S for the mean.

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\Rightarrow *Nullity-implies-independence* is too strong.

Full information gain:

$T(Y|\mathfrak{A}) = T(\delta_Y)$ implies $\xi_S(Y; \mathfrak{A}) = 1$.

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- ◇ Y is \mathfrak{A} measurable $\xi_S(Y; \mathfrak{A}) = 1$.
- ◇ E.g., $\mathfrak{A} = \sigma(\mathbf{X})$; Y and X_i are co-(counter)monotonic

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Monotonicity with respect to nested information:

If $\mathfrak{A} \subseteq \mathfrak{A}'$ then $\xi_S(Y; \mathfrak{A}) \leq \xi_S(Y; \mathfrak{A}')$.

S strictly consistent: $\xi_S(Y; \mathfrak{A}) = \xi_S(Y; \mathfrak{A}')$ only if $T(Y|\mathfrak{A}) = T(Y|\mathfrak{A}')$.

- ◇ $\xi_S(Y; h(\mathbf{X})) \leq \xi_S(Y; \mathbf{X})$, $h: \mathbb{R}^d \rightarrow \mathbb{R}^m$, $d \leq m$

Choice of Scoring Function

A score S is strictly consistent for $T(\cdot) = \mathbb{E}[\cdot]$, iff

$$S_{\phi}(z, y) = \phi(y) - \phi(z) + \phi'(z)(z - y), \quad z, y \in \mathbb{R},$$

for a strictly convex function ϕ with subgradient ϕ' .

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Scale-invariant scores

$$\xi_S(cY; \mathfrak{A}) = \xi_S(Y; \mathfrak{A}) \quad \text{for all } c > 0, \mathfrak{A} \subseteq \mathfrak{F}.$$

Proposition

If S is homogeneous, i.e., $S(cz, cy) = c^b S(z, y)$, for some $b \in \mathbb{R}$, then ξ_S is scale-invariant.

Homogeneous scores for $T(\cdot) = \mathbb{E}[\cdot]$ is the Patton family ($z, y > 0$)²

$$S_b(z, y) = \begin{cases} \frac{y^b - z^b}{b(b-1)} - \frac{z^{b-1}}{b-1}(y - z), & b \in \mathbb{R} \setminus \{0, 1\}, \\ \frac{y}{z} - \log\left(\frac{y}{z}\right) - 1, & b = 0, \\ y \log\left(\frac{y}{z}\right) - (y - z), & b = 1, \end{cases} \quad (2)$$

Unique up to a positive scaling.

²[Nolde & Ziegel, 2017]

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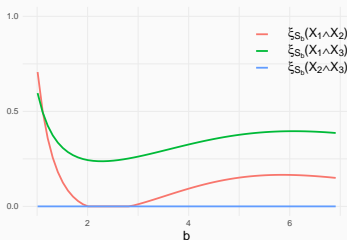
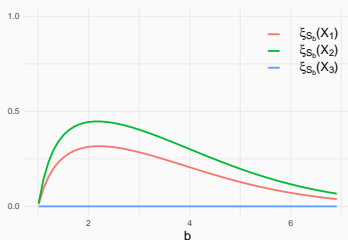
Murphy diagrams for sensitivity measures $b \mapsto \xi_{S_b}(Y; \mathfrak{A})$.

²[Nolde & Ziegel, 2017]

Ishigami–Homma Test Function

$T = \mathbb{E}[\cdot]$, b -homogeneous scores $S(cz, yz) = c^b S(z, y)$:

$$Y = \sin(X_1) + 7 \sin(X_2)^2 + 0.1 X_3^4 \sin(X_1),$$



Interaction information

$$\xi_S(Y; \mathfrak{A}_1 \wedge \mathfrak{A}_2) := \max \{ \xi_S(Y; \sigma(\mathfrak{A}_1 \cup \mathfrak{A}_2)) - \xi_S(Y; \mathfrak{A}_1) - \xi_S(Y; \mathfrak{A}_2), 0 \},$$

Working paper includes

- ◇ multiple examples illustrating the properties
- ◇ Murphy diagrams for elementary scores
- ◇ non-linear insurance example
- ◇ Score-based sensitivity measures to $(\text{VaR}_\alpha, \text{ES}_\alpha)$
- ◇ using neural nets to estimate $T(Y|\mathbf{X})$

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Thank you!

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