PROPORTIONAL MARGINAL EFFECTS FOR SENSITIVITY ANALYSIS WITH CORRELATED INPUTS

Margot Herin^{1,4}, Marouane IL Idrissi^{1,2,3}, Bertrand Iooss^{1,2,3}, Vincent Chabridon^{1,3}

¹ Electricité de France R&D
 ²Institut de Mathématiques de Toulouse
 ³SINCLAIR AI Lab
 ⁴Sorbonne Université (LIP6)

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2. PME

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GSA FRAMEWORK - NOTATIONS

- Inputs: X = (X₁, ..., X_d) real-valued random vector of joint probability measure P_X and marginal probability measures P_{Xi};
- Model: $G: \begin{cases} \mathbb{R}^d \longrightarrow \mathbb{R} \\ X \longmapsto G(X) \end{cases}$, $G \in \mathbb{L}^2(P_X);$
- Output: Y = G(X).

 $\mathcal{P}_d = \mathcal{P}(\{1, ..., d\}).$ $\forall u \in \mathcal{P}_d, \ X_u = (X_i)_{i \in u}.$

Sobol' Indices (Sobol 1990)

$$\forall A \in \mathcal{P}_d, \quad S_A = \frac{\sum_{B \subset A} (-1)^{|A| - |B|} \mathbb{V}(\mathbb{E}[G(X)|X_B])}{\mathbb{V}(G(X))}$$

Under independence assumption ($P_X = \prod_i P_{X_i}$), S_A represents a variance share:

$$\left\{egin{array}{ll} \mathbb{S}_A\geq 0, & orall A\in \mathcal{P}_d\ & \sum\limits_{A\in \mathcal{P}_d} S_A=1. \end{array}
ight.$$



Not true in the general case!

The Sobol' indices can be negative and thus do not consist in a variance decomposition

anymore.

(Da Veiga et al. 2021) 4/20

A cooperative game (D, v) consists of:

- A set of players $D = \{1, ..., d\}$;
- A value function $v : \mathcal{P}_d \to \mathbb{R}^+$ s.t. $v(\emptyset) = 0$.

hyp: $\forall A_1, A_2 \in \mathcal{P}_d \text{ s.t. } A_1 \subseteq A_2, v(A_1) \leq v(A_2).$

An **allocation rule** is a real-valued function ϕ that associates to any cooperative game (D, v) a real valued vector $(\phi)_{i=1,...,d}$.

Shapley values (Shapley 1951)

For all cooperative game (D, v), for all $i \in D$:

$$\operatorname{Shap}_{i}((D, v)) = \sum_{A \subseteq D \setminus \{i\}} \frac{(d - |A| - 1)! |A|!}{d!} (v(A \cup \{i\}) - v(A)).$$

Shapley effects (Owen 2014) (Song, Nelson, and Staum 2016)

 $\forall i \in D, \ \text{Sh}_i = \text{Shap}_i((D, S^T)) \text{ where } \forall A \in \mathcal{P}_d, \ S_A^T = \frac{\mathbb{E}[\mathbb{V}(G(X)|X_{\bar{A}})]}{\mathbb{V}(G(X))}$

L

- variance decomposition in the correlated case;
- input ranking according output variance contribution;
- factor fixing:

 $Sh_i = 0 \Rightarrow \forall A \subseteq D \setminus \{i\}, \ S_{A \cup \{i\}}^T - S_A^T = 0.$ $\Rightarrow X_i \text{ does not contribute to output variance.}$

PB: partial factor fixing since an exogenous variable can get non zero Shapley effect.

Shapley's joke example (looss and Prieur 2019)

$$Y = G(X) = X_1$$

(X₁, X₂) ~ $\mathcal{N}\left(\begin{pmatrix} 0\\ 0 \end{pmatrix}, \begin{pmatrix} 1& \rho\\ \rho & 1 \end{pmatrix}\right)$

 $Sh_1 = 1 - \frac{\rho^2}{2}$ $Sh_2 = \frac{\rho^2}{2}$

2. PME

DEFINITION

Marginal proportional values (PMV) (Feldman 2005)

For all cooperative game (D, v) with v valued in \mathbb{R}^{+*} (extension to \mathbb{R}^{+} provided in this work)

$$\mathsf{PV}_i\left((D,v)\right) = \frac{R(D,v)}{R(D\setminus\{i\},v)}$$

where *R* is defined recursively by:

$$\forall A \in \mathcal{P}(D), \ R(A,v) = v(A) \left(\sum_{j \in A} \frac{1}{R(A \setminus \{j\}, v)}\right)^{-1} and \ R(\emptyset, v) = 1$$

Proportional Marginal Effects (PME)

$$\forall i \in D, \ \mathsf{PME}_i = \mathsf{PV}_i((D, S^T))$$

$$\left\{ egin{array}{ll} \sum_{i} \mathsf{PME}_{i} = 1 & (\textbf{Efficiency property}) \ orall i \in D, & \mathsf{PME}_{i} \geq 0 \end{array}
ight.$$

PME = Shapley effects alternative to provide variance decomposition with correlated input.

AXIOMATIC: INTERACTION REPARTITION

Balanced contribution property	Equal proportional gain property	
$\forall i, j \in D, \ \mathrm{Sh}_i - \mathrm{Sh}_{i,-j} = \mathrm{Sh}_j - \mathrm{Sh}_{j,-i}$	$\forall i, j \in D,$	$rac{PME_i}{PME_{i,-j}} = rac{PME_j}{PME_{j,-i}}$

where $\phi_{i,-i}$ refer to the variance share of X_i without including the variance due to the interaction with X_i .

Illustration for $D = \{1, 2\}$: $\forall i \in D, D = \{i, \overline{i}\}, \phi_{i, -\overline{i}} = S_i^T$ (individual value)



Figure 1: Schematic illustration of the interaction distribution (left: Shapley effects/ right : PME).

Shapley's joke example

$$Y = X_1$$

$$(X_1, X_2) \sim \mathcal{N}\left(\left(\begin{array}{c} 0\\ 0 \end{array} \right), \left(\begin{array}{c} 1 & \rho\\ \rho & 1 \end{array} \right) \right)$$

$$S_1^T > 0, Sh_1 = 1 - \frac{\rho^2}{2}, PME_1 = 1.$$

 $S_2^T = 0, Sh_2 = \frac{\rho^2}{2}, PME_2 = 0.$

Proposition

Suppose that there exists a subset of endogenous variable $D^* \subseteq D$ of size d^* such that $\forall i \in D^*$, $S_i^T > 0$ and such that one can find a measurable function f that verifies $Y = G(X) = f(X_{D^*})$. Then:

 $\forall i \notin D^*, PME_i = 0.$

CONSEQUENCE : ROBUSTNESS TO CORRELATION (EXAMPLE II)

Linear gaussian case:

$$Y = X_{1} + \beta_{2}X_{2} + X_{3}$$

$$(X_{1}, X_{2}, X_{3}) \sim \mathcal{N} \left(\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & \rho \\ 0 & \rho & 1 \end{pmatrix} \right)$$

$$Sh_{1} = PME_{1} \xrightarrow{\rho \to 1} \frac{1}{2 + \beta_{2}^{2} + 2\beta_{2}} \qquad \beta_{2} \gg 1^{0}$$

$$Sh_{2}, Sh_{3} \xrightarrow{\rho \to 1} \frac{\frac{1}{2}\beta_{2}^{2} + \beta_{2} + \frac{1}{2}}{2 + \beta^{2} + 2\beta_{2}} \qquad \beta_{2} \gg 1^{0}$$

$$PME_{2} \xrightarrow{\rho \to 1} \frac{\beta_{2}^{2}(1 + \beta_{2}^{2} + 2\beta_{2})}{(2 + \beta^{2} + 2\beta_{2})(1 + \beta_{2}^{2})} \qquad \beta_{2} \gg 1^{0}$$

$$PME_{3} \xrightarrow{\rho \to 1} \frac{(1 + \beta_{2}^{2} + 2\beta_{2})(1 + \beta_{2}^{2})}{(2 + \beta^{2} + 2\beta_{2})(1 + \beta_{2}^{2})} \qquad \beta_{2} \gg 1^{0}$$



Figure 2: Shapley effects and PME indices w.r.t to $\rho_{11/20}$ for $\beta_2 = 10$. Input X_1, X_2, X_3 from up to down.

2. PME

2-step estimation procedure (similar to the Shapley effects estimation):

- Estimation of the conditional elements S_A^T , $\forall A \in \mathcal{P}_D$:
 - Monte Carlo estimation (Song, Nelson, and Staum 2016);
 - Data-given estimation using a nearest-neighbor procedure (Broto, Bachoc, and Depecker 2020).
- <u>Aggregation procedure</u> by plugging-in the estimated conditional elements in the PME recursive formula.

 \longrightarrow package sensitivity in R

APPLICATION A TO REALISTIC MODEL

Robot arm model (An and Owen 2001)

- inputs: angles (*A_i*) and lengts (*L_i*) of 4 segments of the arm;
- output : extension of the arm

$$Y = \left\{ \left[\sum_{i=1}^{4} L_i \cos\left(\sum_{j=1}^{i} A_j\right) \right]^2 + \left[\sum_{i=1}^{4} L_i \sin\left(\sum_{j=1}^{i} A_j\right) \right]^2 \right\}^{1/2}$$

• The inputs are artificially correlated:

- ∀A_i ~ U[0, 2π], pairwise correlated with Gaussian copula with a 95% correlation coeff;
- $L_1 \sim \mathcal{U}[0,1], \forall i > 1, L_i \sim \mathcal{U}[0,L_{i-1}]$



Figure 3: Pair plots of a 2000-size Monte Carlo sample for the robot arm model.

APPLICATION A TO REALISTIC MODEL



Shapley effects estimation by nearest-neighbor procedure Proportional marginal effects estimation by nearest-neighbor procedure

Figure 4: Shapley effects (left) and PME (right) for the robot arm model.

CONCLUSION

PME indices allow for another variance decomposition in the correlated case with new properties:

- Equal proportional gain : interaction is shared proportionaly to individual power. The three following points can be seen as valuable consequences of this property.
- Robustness to correlation when interaction = correlation;
- No Shapley's joke: an exogenous input always get zero % variance share, even if it is correlated to endogenous variable;
- Strong discrimination between inputs.





Figure 5: Schematic illustration of PME (right) and Sh (left) indices for d = 3.

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- Finite sample properties of the estimator?
- A PME equivalent of the Shapley-Owen indices (Rabitti and Borgonovo 2019) (Shapley effects quantifying group importance)?

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SUPPLEMENTARY MATERIAL

Proportional values extension

$$\forall i \in D, \ \widetilde{\mathsf{PV}}_i((D, v)) = \begin{cases} \sum_{\substack{S \subseteq D_{-i} \\ |S| = k_M \\ v(S) = 0 \\ S \subseteq D \\ |S| = k_M \\ v(S) = 0 \\ \\ 0 \\ 0 \\ \end{cases} \text{ if } \exists S \subseteq D_{-i} \ s.t \ |S| = k_M, \ v(S) = 0, \\ R(D \setminus S, v_S)^{-1} \\ \text{ if } \exists S \subseteq D_{-i} \ s.t \ |S| = k_M, \ v(S) = 0, \end{cases}$$

where k_M is the size of the largest null coalition, i.e., $k_M = k_M((D, v)) = \max_{T \subseteq D} \{ |T| | v(T) = 0 \}$

Allocation reduce game:

$$\phi_{i,-j} = \phi_i(D \setminus \{j\}, v), \quad \sum_{i \neq j} \phi_{i,-j} = v(D \setminus \{j\})$$